

CT Convolution

# CT Signals and Systems – Response of a CT LTI System

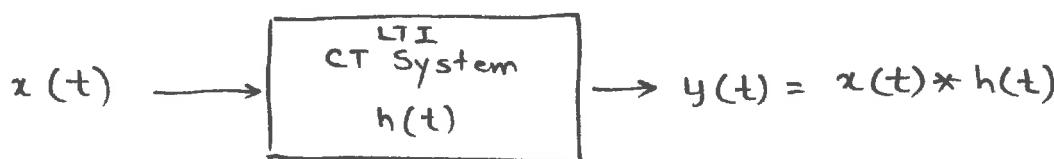
For DT  $y[n] = x[n] * h[n] \triangleq \sum_{k=-\infty}^{\infty} x[k] h[n-k]$

## Convolution Integral

$$y(t) = x(t) * h(t) \triangleq \int_{-\infty}^{\infty} x(\tau)h(t - \tau) d\tau$$

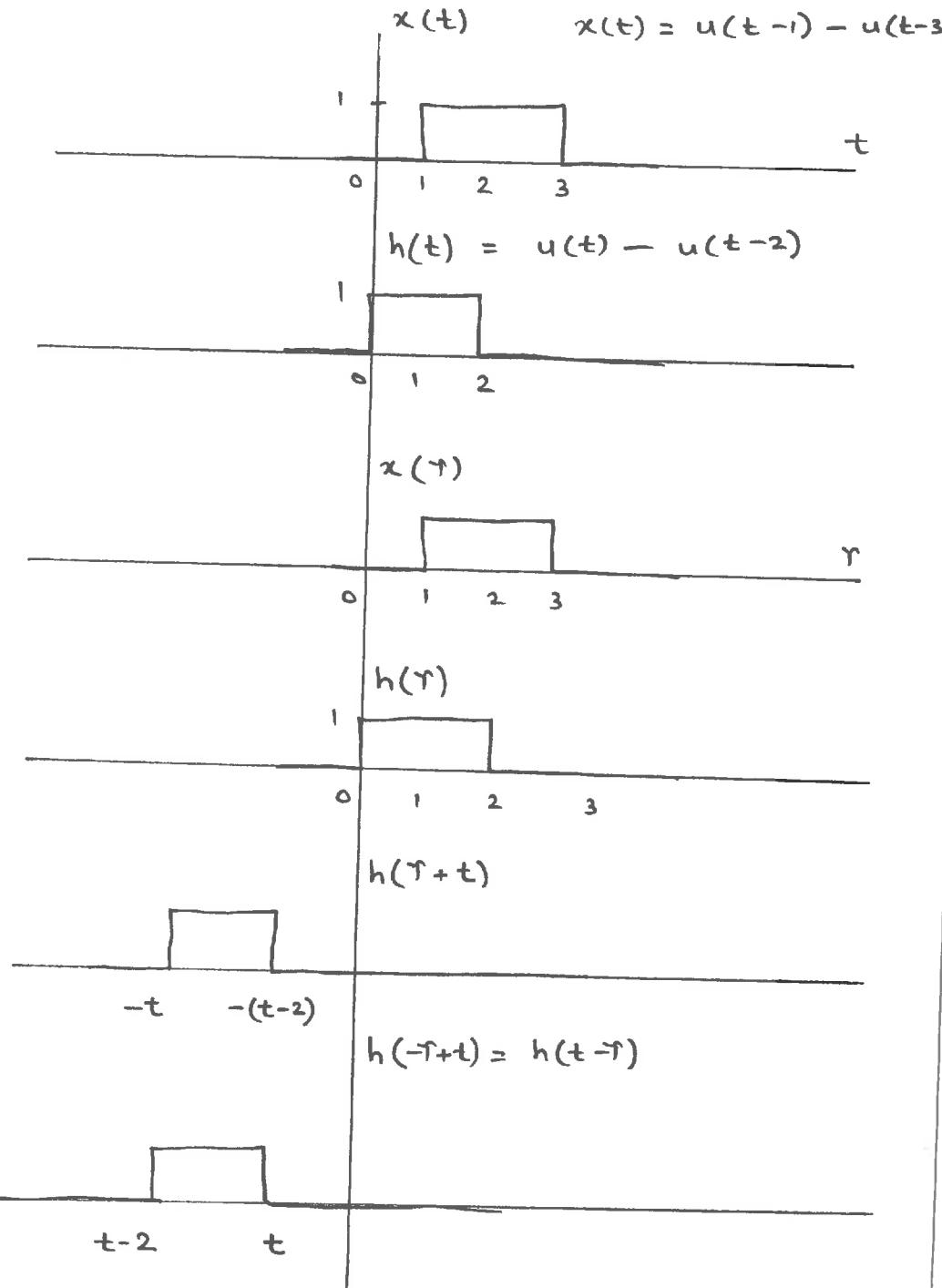
### Interpretation

$$\begin{aligned} h(\tau) &\xrightarrow{\text{Flip}} h(-\tau) \\ h(-\tau) &\xrightarrow{\text{Shift}} h(t - \tau) \\ h(t - \tau) &\xrightarrow{\text{Multiply}} x(\tau)h(t - \tau) \\ x(\tau)h(t - \tau) &\xrightarrow{\text{Integrate}} \int_{-\infty}^{\infty} x(\tau)h(t - \tau) d\tau \end{aligned}$$



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## CT Convolution Example



For  $t < 1$  There is no overlap,  $y(t) = 0$

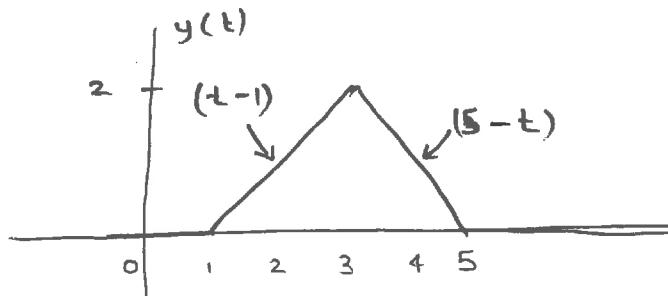
For  $1 \leq t \leq 3$

$$\begin{aligned} y(t) &= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \\ &= \int_1^t (1)(1) d\tau = \left| \tau \right| \Big|_1^t = t - 1 \end{aligned}$$

For  $3 \leq t \leq 5$

$$\begin{aligned} y(t) &= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \\ &= \int_{t-2}^3 (1)(1) d\tau \\ &= \left| \tau \right| \Big|_{t-2}^3 = 5 - t \end{aligned}$$

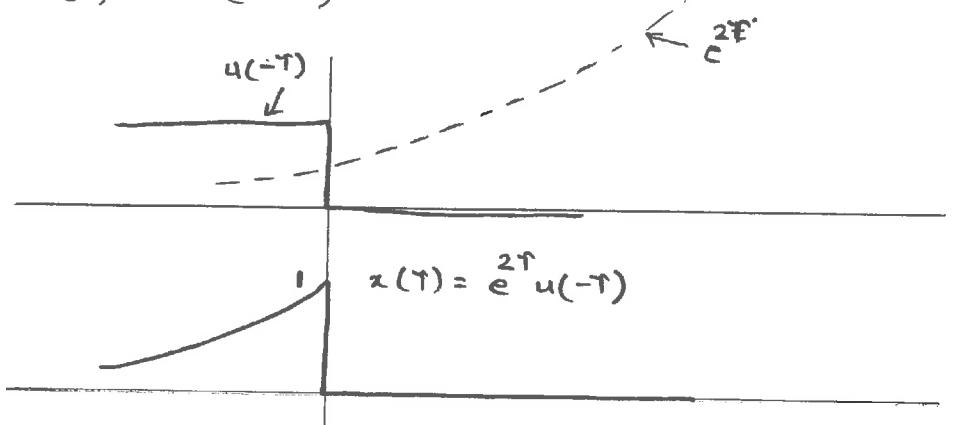
For  $t \geq 5$  no overlap,  $y(t) = 0$ .



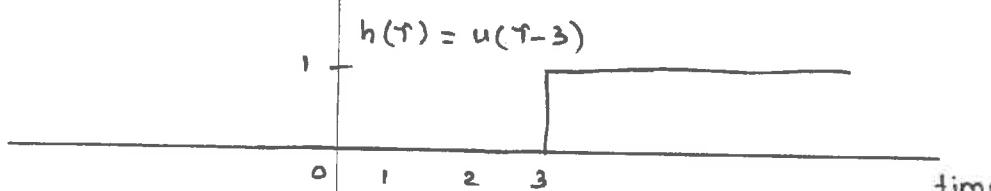
## CT Convolution Example 2

$$x(t) = e^{2t} u(-t)$$

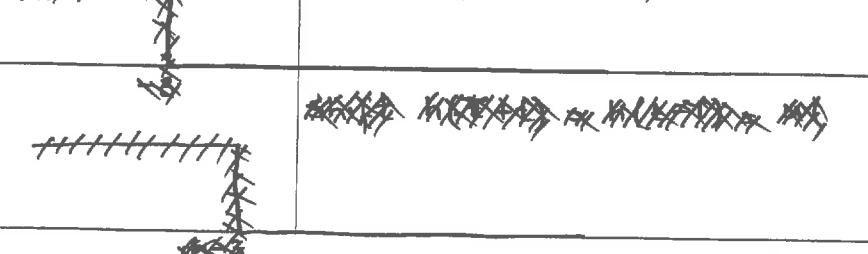
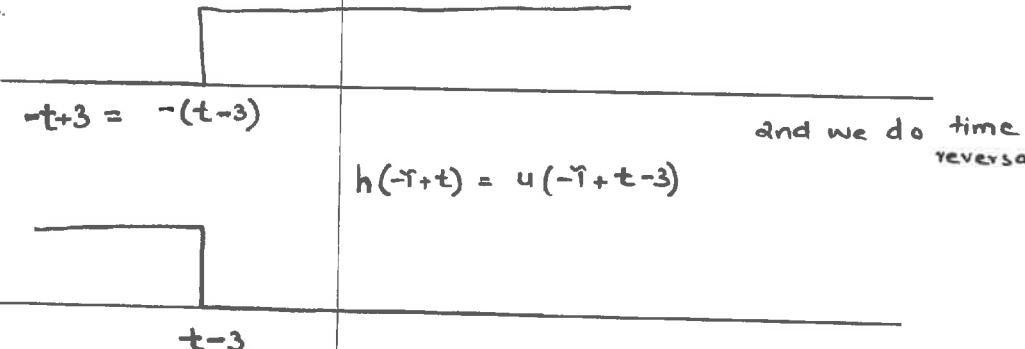
$$h(t) = u(t-3)$$



$$x(\tau) = e^{2\tau} u(-\tau)$$



$$h(\tau+t) = u(\tau+t-3) \quad \text{1st we do shift}$$



$$\text{For } t-3 < 0 \\ \Rightarrow t < 3$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^{t-3} e^{2\tau} d\tau$$

$$= \frac{1}{2} \left| e^{2\tau} \right|_{-\infty}^{t-3} = \frac{1}{2} \left( e^{2(t-3)} - e^{-\infty} \right)$$

$$= \frac{1}{2} e^{2(t-3)}$$

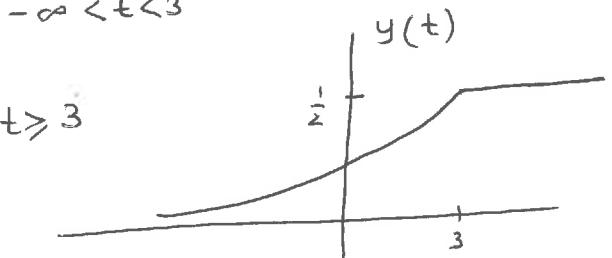
$$\text{For } t-3 \geq 0 \\ \Rightarrow t \geq 3$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^0 e^{2\tau} d\tau$$

$$= \frac{1}{2} \left| e^{2\tau} \right|_{-\infty}^0 = \frac{1}{2} \left( e^0 - e^{-\infty} \right) = \frac{1}{2} (1 - 0) = \frac{1}{2}$$

$$y(t) = \begin{cases} \frac{1}{2} e^{2(t-3)} & -\infty < t < 3 \\ \frac{1}{2} & t \geq 3 \end{cases}$$



## Properties of Impulse & Unit Step Functions

(1) How to visualize  $\delta(t)$

(2) Relationship between  $u(t)$  and  $\delta(t)$

(3) Convolution with  $\delta(t)$

(4) Sifting property of  $\delta(t - t_0)$



Note :

$$x(t) * h(t) = h(t) * x(t) \rightarrow \text{Commutative property.}$$

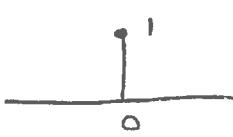
$$x(t) * (h_1(t) + h_2(t)) = x(t) * h_1(t) + x(t) * h_2(t) \rightarrow \text{Distributive property}$$

$$x(t) * (h_1(t) * h_2(t)) = (x(t) * h_1(t)) * h_2(t) \rightarrow \text{Associative property.}$$

## Properties of $\delta(t)$

DT unit Impulse

$$\delta[n] = \begin{cases} 1 & n=0 \\ 0 & n \neq 0 \end{cases}$$



$$\delta(at) = \frac{1}{a} \delta(t), \quad a > 0 \Rightarrow \text{time-scaling property.}$$

CT unit Impulse is defined by following pair of equations

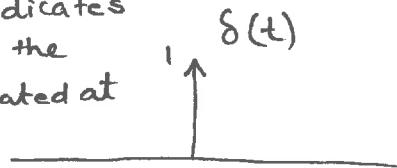
$$\delta(t) = 0 \text{ for } t \neq 0 \quad \&$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1.$$

↑  
total area  
under the unit  
impulse is unity.

↑  
impulse is zero  
everywhere, except at  
origin.

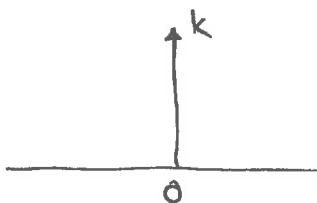
arrow at  $t=0$  indicates  
that the area of the  
impulse is concentrated at  
 $t=0$ .



Dirac delta  
function.

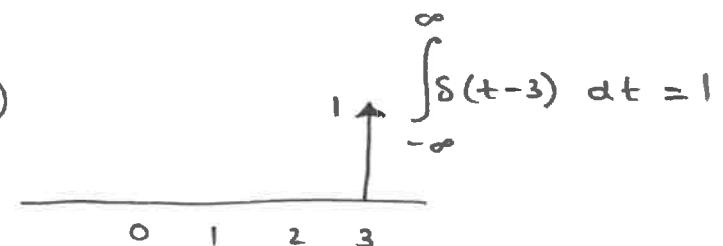
The height of the arrow and the '1' next to it represent  
the area of the impulse.

Sketch  $k\delta(t)$

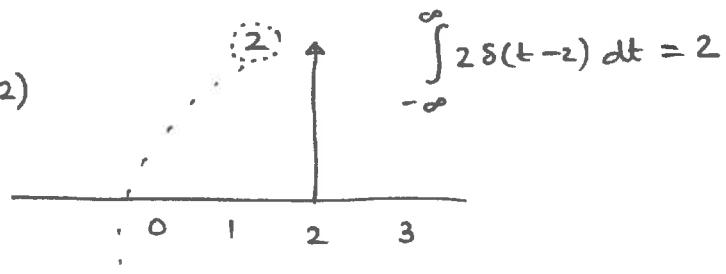


Scaled  
Impulse

$$\delta(t-3)$$



$$2\delta(t-2)$$



This is indicating area under the  
impulse function.

## CT System Properties – Sifting Property (cont'd)

Note that  $x(t) \star \delta(t - t_0)$  is different from  $x(t) \delta(t - t_0)$ . The expression on the left is convolution of two signals and the expression on the right is pointwise multiplication.

- Convolution

$$\begin{aligned}x(t) \star \delta(t - t_0) &= \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau - t_0) d\tau \\&= x(t - t_0)\end{aligned}$$

- Pointwise multiplication

$$x(t) \delta(t - t_0) = x(t_0) \delta(t - t_0)$$

which is a scaled impulse response.



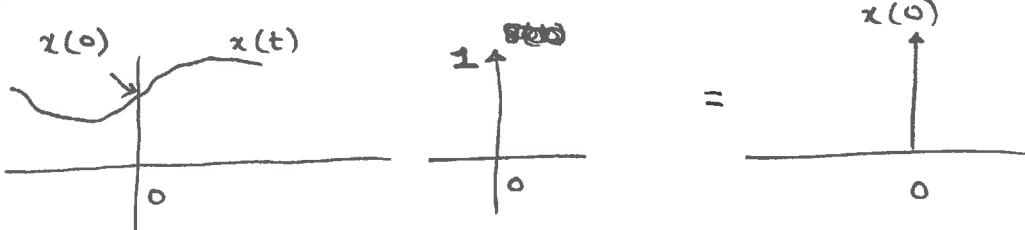
## Sifting Property of Impulse

$$\textcircled{2} \int_{-\infty}^{\infty} x(t) \delta(t-t_0) dt = x(t_0)$$

$$\textcircled{1} x(t) \delta(t-t_0) = x(t_0) \delta(t-t_0)$$

↑  
pointwise  
multiplication

$$x(t) \delta(t) = x(0) \delta(t)$$



$$\textcircled{3} x(t) * \delta(t-t_0) = x(t-t_0)$$

↑  
convolution

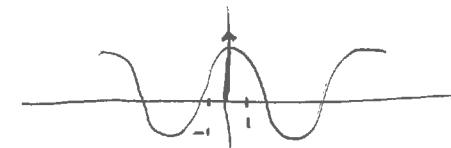
convolving a signal with an impulse shifts the signal to the location of the impulse.

### Examples

$$\int_{-\infty}^{\infty} x(t) \delta(t) dt = x(0)$$

$$\int_{-\infty}^{\infty} x(t) \delta(t-5) dt = x(5)$$

$$\int_{-1}^1 \cos t \delta(t) dt = \cos 0 = 1$$

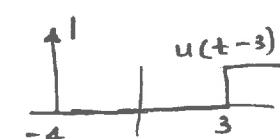


$$\int_1^3 \cos t \delta(t) dt = 0 \quad (\text{since } \delta(t)=0 \text{ between } 1 \leq t \leq 3)$$

$$\int_1^3 \cos t \delta(t-2) dt = \cos 2 \quad (\text{since } \delta(t-2)=1 \text{ at } t=2 \text{ and this is inside the integration range})$$

$$\int_{-\infty}^{\infty} e^{-4(t-1)} \delta(t-2) dt = \frac{-4(2-1)}{e} = \frac{-4}{e}$$

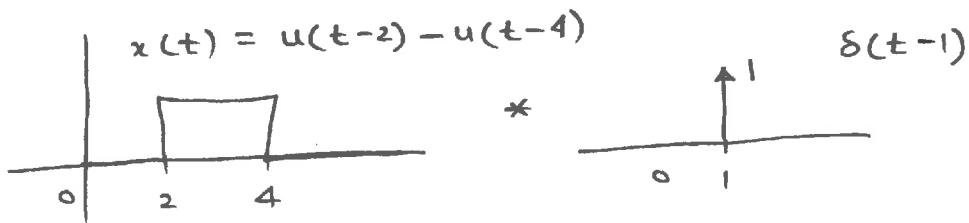
$$\int_{-\infty}^{\infty} u(t-3) \delta(t+4) dt = 0$$



## Convolution with Impulses

$$x(t) * \delta(t - t_0) = x(t - t_0)$$

Example



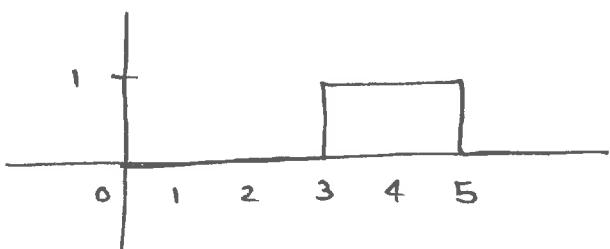
$$x(t) * \delta(t-1) = (u(t-2) - u(t-4)) * \delta(t-1)$$

$$\rightarrow = u(t-2) * \delta(t-1) - u(t-4) * \delta(t-1)$$

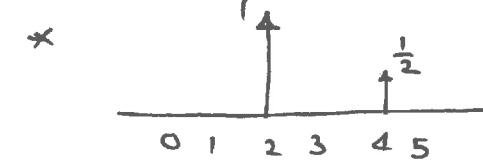
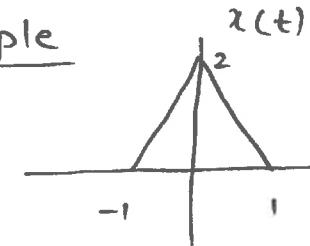
distributive  
property of  
convolution.

$$= u(t-1-2) - u(t-1-4)$$

$$= u(t-3) - u(t-5)$$



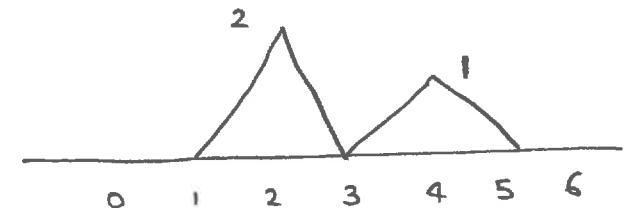
Example



$$x(t) * \left[ \frac{\delta(t-2)}{2} + \frac{1}{2} \delta(t-4) \right]$$

$$= x(t) * \frac{\delta(t-2)}{2} + \frac{1}{2} x(t) * \delta(t-4)$$

$$= x(t-2) + \frac{1}{2} x(t-4)$$



Example

$$h(t) = \delta(t+1) - \delta(t) + 2\delta(t-2)$$

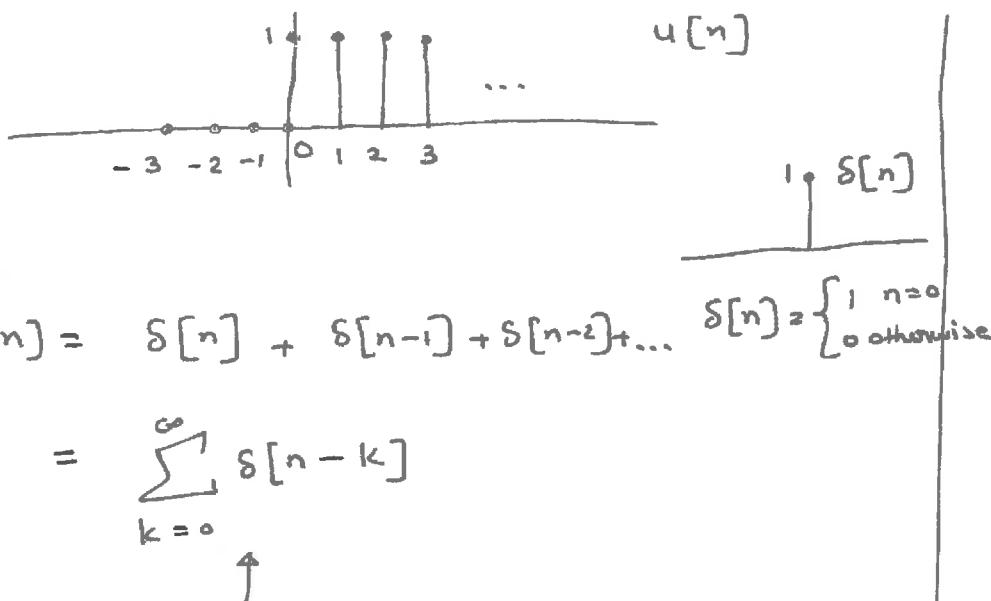
$$x(t) = e^{-t} u(t)$$

$$y(t) = x(t) * h(t)$$

$$= e^{-(t+1)} u(t+1) - e^{-t} u(t) + 2e^{-(t-2)} u(t-2)$$

# Froon L05 notes

## Representing DT Signals using unit Impulse functions



unit-step = superposition of delayed impulses

$$u[n] = \sum_{k=-\infty}^n \delta[k]$$

DT unit step = running sum of the unit impulse.

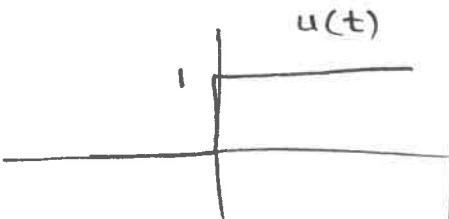
$$\delta[n] = u[n] - u[n-1]$$

unit impulse = first difference of DT unit step

## Relationship with $u(t)$

### Unit Step Function

$$u(t) = \begin{cases} 0 & t < 0 \\ 1 & t \geq 0 \end{cases}$$



CT unit step is the running integral of the unit impulse

$$u(t) = \int_{-\infty}^t s(\tau) d\tau$$

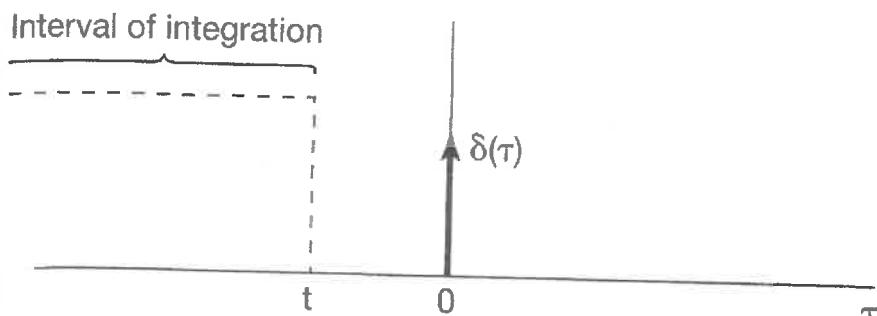
$$s(t) = \frac{d}{dt} u(t)$$

CT unit impulse can be thought of as the 1st derivative of the CT unit-step.

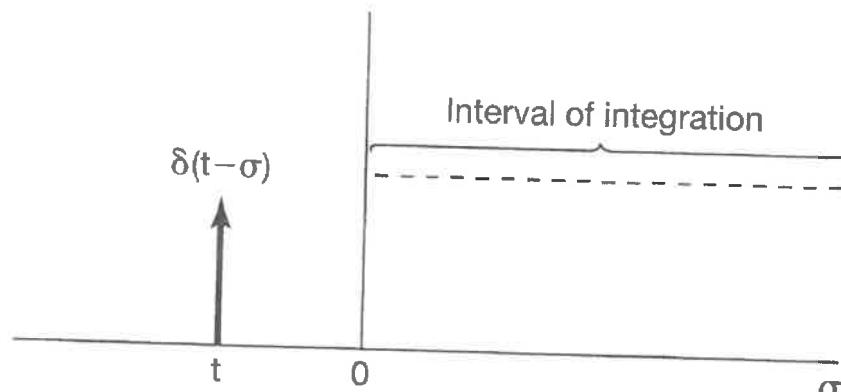
Another way to relate  $u(t)$  &  $s(t)$

$$u(t) = \int_0^\infty s(t-\sigma) d\sigma$$

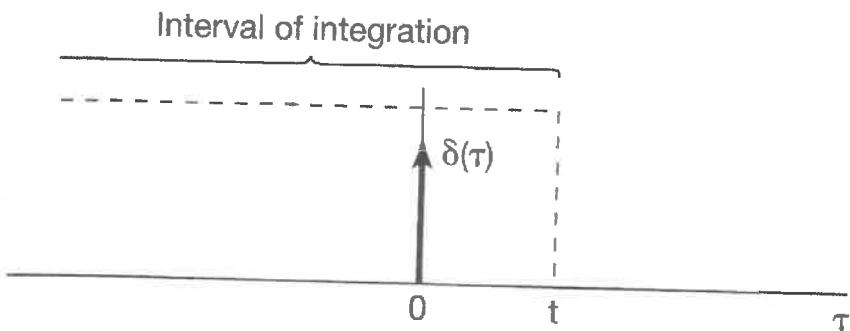
Since area of  $s(t-\sigma)$  is concentrated at point  $\sigma=t$ , the integral is 0 for  $t < 0$  and 1 for  $t > 0$ .



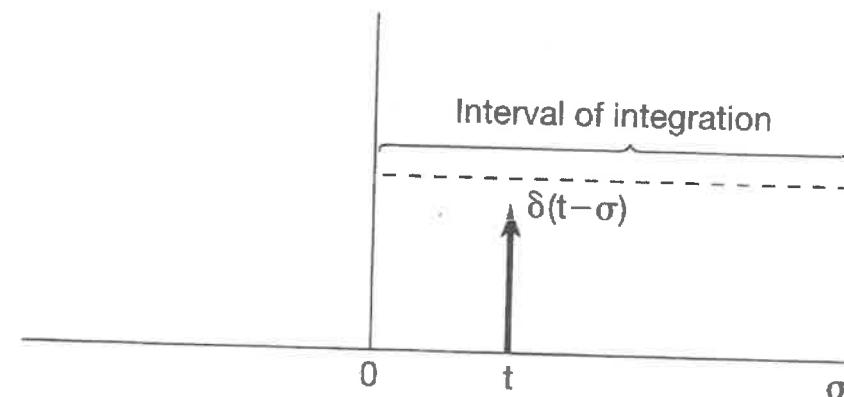
(a)



(a)



(b)



(b)

**Figure 1.37** Running integral given in eq. (1.71):  
 (a)  $t < 0$ ; (b)  $t > 0$ .

**Figure 1.38** Relationship given in eq. (1.75):  
 (a)  $t < 0$ ; (b)  $t > 0$ .

## Impulses and More – Additional Results (cont'd)

We can represent this as:

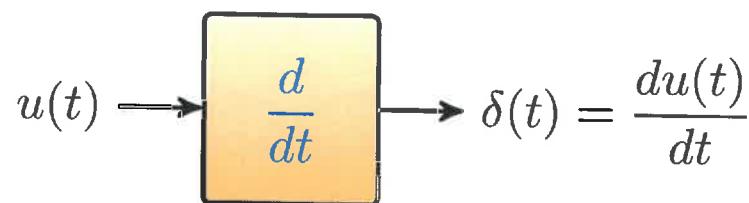


Fig: Differentiator with Unit Step Input

where the  $\frac{d}{dt}$  inside the box is not the impulse response but denotes an operator. (cont'd)

